

Making decisions for frost prediction in agricultural crops in a soft computing framework

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Abstract

Nowadays, there are many areas of daily life that can obtain benefit from technological advances and the large amounts of information stored. One of these areas is agriculture, giving place to precision agriculture. Frosts in crops are among the problems that precision agriculture tries to solve because produce great economic losses to farmers. The problem of early detection of frost is a process that involves a large amount of wheather data. However, the use of these data, both for the classification and regression task, must be carried out in an adequate way to obtain an inference with quality. A preprocessing of them is carried out in order to obtain a dataset grouping attributes that refer to the same measure in a single attribute expressed by a fuzzy value. From these fuzzy time series data we must use techniques for data analysis that are capable of manipulating them. Therefore, first a regression technique based on k -nearest neighbors in a Soft Computing framework is proposed that can deal with fuzzy data, and second, this technique and others to classification are used for the early detection of a frost from data obtained from different weather stations in the Region of Murcia (south-east Spain) with the aim of decrease the damages that these frosts can cause in crops. From the models obtained, an interpretation of the provided information is performed and the most relevant set of attributes is obtained for the anticipated prediction of a frost and of the temperature value. Several experiments are carried out on the datasets to obtain the models with the best performance in the prediction validating the results by means of a statistical analysis.

Keywords: Precision agriculture, crop frost, data analysis, fuzzy data, fuzzy classification and regression, fuzzy k -nearest neighbors, fuzzy decision tree

1. Introduction

1 Agriculture plays a very important role in the economy of a country. Precision agriculture, now also called digital
2 agriculture, and the development of technologies applied to it have emerged as fields that use data-intensive approaches
3 to control productivity while minimizing its environmental impact. The data generated, directly and indirectly, in
4 the environment of agricultural crops are provided by different sensors. These sensors obtain information on crop
5 products, soil, climatic conditions, etc. allowing a better understanding of the environment and the operation itself.
6 All this will lead to faster, more efficient and effective decision-making systems, (Liakos et al., 2018).
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8 Among many other factors, frosts are meteorological phenomena that cause relatively frequent major damage to
9 the proper development of an agricultural crop. Sometimes these crop frosts are severe and constitute a real potential
10 threat (García-Pedraza and García-Vega, 1991). Frost is influenced by climatic conditions and, among other, by local
11 factors such as topography and terrain orientation, soil types, etc. The study carried out in (García-Pedraza and
12 García-Vega, 1991) highlights that local factors (type of soil, orientation of slopes to the North (shady) or to the South
13 (sunny)) influence frost. Also the damage that a frost can cause to crops depends on the intensity and duration of
14 the frost. In (García-Pedraza and García-Vega, 1991; Lee et al., 2016) frosts are classify as “Advection frosts (black
15 frosts)”, “Evaporation frosts” and “Irradiation frosts”. In Spain the latter are the most frequent, covering the period
16 autumn-winter-spring. Late spring frosts are usually the most dangerous for crops.

17 On the “FreshPlaza” website (an independent source of news for companies operating on a global scale in the
18 agricultural sector, particularly fruit and vegetables) there are articles and news related to the sector. Among others,
19 news related to economic losses caused by frost can be found, (Fresh Plaza, 2018, 2019).

20 In (Fresh Plaza, 2018), the concern in southern Europe about frost damage to early stone fruit is again described
21 for 2018. In March spring begins in the weather calendar however, the cold continues to occur. The strong east
22 wind causes temperatures to fall well below freezing in many parts of Europe. Cold and snow disrupt life in several
23 European countries with serious market consequences. In particular, the consequences in southern and eastern Europe
24 (such as Spain, Italy, northern France, western Hungary, Croatia, etc.) caused by these inclement weather conditions
25 have affected some types of fruit trees that were already in bloom or about to bloom. Extreme cold damages the early
26 harvest of stone fruit in these regions.

27 In (Martínez-Núñez et al., 2015) a study of frost and cold hours in Spain is presented during the period 2002-2012
28 from November to April. The authors use different threshold temperatures for their study. Among them, temperatures
29 below 7°C are considered as a fixed value in the determine the hours of cold.

30 The map of frosts in Spain presented in that study is very interesting, analysing both the agricultural and economic
31 repercussions of cold hours. They present maps describing the number of frost days/year, frost probabilities/year, dates
32 of both the first and last frosts, etc. Among the areas described, the Region of Murcia stands out for its agricultural
33 features. The Region of Murcia (Southeast Spain) suffers during the winter season and early spring of various stages
34 of frost which causes damage to the flower and/or fruit. These frosts produce considerable losses to the sector, and
35 there is a need for reliable warning systems to prevent such damage in some cases (the loss caused by frost in March
36 2019 is estimated at 14.7 million euros in several areas) (Fresh Plaza, 2019).

37 In (Snyder et al., 2010) there is also an analysis for frost in crops. The analysis of frost prediction and monitoring,
38 and of the various passive and active methods for frost protection is very interesting. In this paper, the authors highlight
39 the value of effective prediction involving complex analysis of decision making, but importantly, accurate prediction
40 would allow farmers to prepare against them and potentially reduce the damage they can cause.

41 In conclusion, frosts produce significant losses to the agricultural sector which need to develop and have effective
42 strategies and reliable warning systems to prevent or reduce damage to crops, loss of fruit quality and/or production
43 losses. Thus, this manuscript focuses on the development of a decision system based on fuzzy models for the frost
44 prediction with the aim of informing and alerting. With this information farmers can activate anti-frost techniques and

45 thus avoid losing their crops. To this purpose, the objectives in this manuscript are as follows:

- 46 • First of all we focus on the information used for the modeling and prediction of frosts. The information pro-
47 vided by institutional systems related to weather can be used in a most appropriate way. For example, systems
48 provide periodic information such as “Minimum, Mean and Maximum relative humidity”, “Mean and Maxi-
49 mum wind speed ”, etc. In general, models use this information as variables or attributes independent of the
50 instances necessary for the frost prediction process. For example, the minimum, mean and maximum of relative
51 humidity refer to the same attribute and not to three independent ones. For this reason, we propose the use of
52 fuzzy information to represent the values of the same measure, interpreting those values more appropriately. In
53 addition, with this representation, the instances are defined by fewer attributes which facilitates the manipulation
54 and subsequent interpretation. Once the information has been preprocessed and the datasets have been obtained
55 with the fuzzy information, the design and use of appropriate techniques for its manipulation are proposed.
- 56 • Next, we focus on the study and characterization of the relationships between the weather attributes to predict
57 frosts, and on the use and/or design of adequate techniques to manipulate the datasets and obtain a good per-
58 formance in the prediction. Therefore, the objective is to find relationships between the weather information
59 obtained several hours before with the prediction that a frost will occur some time later. This helps us to find
60 traces that can characterize these relationships and to build predictive models with good behavior. The final
61 purpose is to build a decision system that helps predict frost. In addition, designed models must be simple using
62 fewer attributes without loss of accuracy.
- 63 • Finally, a new approach based on k -nearest neighbors is proposed. This approach is able to manage imprecise
64 information implicitly in data to tackle the regression task. This technique is applied to the problem presented
65 in this manuscript, that is, to predict the minimum temperature considering several weather attributes.

66 In summary, the proposed decision support system provides the farmer with both qualitative information (whether
67 there will be frost or not) using a classification technique and quantitative information (minimum temperature in the
68 next hour) using a proposed new regression technique. In addition, the characterisation of the most important weather
69 attributes indicates the measuring instruments needed to be able to obtain this information locally in each plot, saving
70 costs since the number of these instruments is smaller.

71 Thus, this manuscript is organized as follows. In Section 2 a background on the automatic systems applied in
72 agriculture is provided, paying special attention to frost prediction systems. In Section 3, a novel approach based on
73 k -nearest neighbours for the regression task that is capable of supporting fuzzy information is presented. In Section
74 4 the datasets, techniques and methods used for the study of early prediction of frost in crops in south-east Spain are
75 described. Specifically, in Subsection 4.1, the study areas where collecting weather information are presented. In
76 addition, from the available information, a preprocessing is carried out with special attention to the transformation
77 into fuzzy values. In Subsection 4.2, the techniques used in the experiments, and their configurations are indicated. In
78 addition, in Subsection 4.3, the different measures and statistical tests used to evaluate the results are commented. In
79 Section 5, all experiments aimed at answering the various questions raised are developed. For the result evaluation and

80 conclusions obtained, statistical tests are applied. Finally, in Section 6, a decision system with its component elements
81 is described and the conclusions are presented in Section 7.

82 **2. Background**

83 Automatic systems built for agriculture are often used for decision making at different levels (Yelapure and Kulka-
84 rni, 2012): a) in the operational level the system is often used to provide advice to producers; and b) in the planning
85 level the system is used to predict the plantation needs.

86 Since the 1970s, decision support systems begin to be built and applied in the agricultural area. Since, these
87 systems have been applied, among others, to the protection breeding, poultry raising, installation horticulture manage-
88 ment, aquaculture activity, plant crops management as well as economical decision making. In (Liakos et al., 2018;
89 Yelapure and Kulkarni, 2012), a very good compilation of these systems can be find. Specifically, a review of different
90 expert system and fuzzy expert systems are detailed.

91 In this manuscript we focus on precision agriculture based on computational learning. More specifically, our
92 proposal focus on the crop management activity of predicting weather conditions, trying to predict frost as one of the
93 problems that affects the quality of producers and the economy of the farmer. Therefore, to focus on the prediction of
94 weather conditions, next this agricultural activity is analyzed.

95 For the prediction and construction of alert systems for frosts in agriculture, different techniques have been pro-
96 posed such as neural networks, self-organizing maps, decision trees, support vector machines (SVM), rule based
97 systems, etc, using data provided by automatic systems witch obtain weather conditions given by time series. Then,
98 some studies are analyzed emphasizing the data and attributes used and the approaches presented.

99 In (Lee et al., 2016) two models for frost prediction or warnings in the spring of Korea are developed using a
100 decision tree and logistic regression. These models were compared using data obtained from 1973 to 2004 from six
101 weather stations and seven attributes. The attributes used were the minimum temperature, grass minimum temperature,
102 mean relative humidity, dew point, minimum relative humidity, wind and cloud. The conclusion reached indicates that
103 the decision tree may be more useful for the frost alert system.

104 In (Fuentes et al., 2018) a neural network model is presented to predict the minimum air temperature of the next
105 day. For the model construction the meteorological data are used such as wind direction and speed, relative humidity,
106 air temperature, precipitation and radiation. The model was validated with 10 weather stations in central Chile for 8
107 years (from 2010 to 2017). The mean square error in the prediction of the minimum temperature was 2.99°C ; and
108 a total average accuracy in the frost detection of 98% (86% sensitivity). The authors highlight that differences and
109 errors in the frost detection can be attributed to factors mainly associated with the accuracy of the weather stations,
110 local climatic and geographical conditions, and the parameter number in the construction of the models.

111 In (Yu et al., 2016) a model based on least squares SVM is proposed. The model parameters are optimized by
112 particle swarm for the anticipated temperature prediction in the Chinese solar greenhouse. The model uses data on
113 indoor and outdoor temperature, indoor air humidity, outdoor solar radiation, wind speed, and soil temperature and
114 humidity of two greenhouses. The obtained conclusions indicate that the proposed model is accurate and therefore
115 useful and effective in predicting the temperatures of the Chinese solar greenhouse.

116 In (Smith et al., 2009) a neural network for predicting air temperature based on near real-time data is applied. The
117 learning and subsequent validation of the models was carried out based on meteorological data from the southeastern
118 United States (Georgia). The models used current values and previous observations of relative humidity, wind speed,
119 temperature and solar radiation. An improvement in the prediction accuracy could be observed when the rain attribute
120 was used. The time values were coded as four values using triangular membership functions in the range [0,1] (mid-
121 night, morning, noon and evening). Similarly, day of the year values were coded using four triangular membership
122 functions to represent seasonality. In total, data with 258 attributes were used. The neural network provided predic-
123 tions for a test dataset of 0.516°C of mean absolute error in the one hour horizon and of 1.873°C of mean absolute
124 error in the twelve hour horizon.

125 In (Efendi et al., 2017) a procedure based on a fuzzy random auto-regression time series is proposed to model the
126 variability and temperature trend. A relevant topic of this work is the transformation of minimum-maximum data into
127 triangular fuzzy numbers. The support of these fuzzy numbers is defined by the minimum and maximum values with
128 membership degree 0 and the midpoint with membership degree 1.

129 A study to predict low temperatures is presented in (Guillén-Navarro et al., 2018). This initial study uses C4.5
130 decision tree and M5P rule techniques (implementations provided by Weka package) to classify possible frosts. For
131 this, the authors use three datasets obtaining a classification error of 12%. Later the authors extend this study in
132 (Guillén-Navarro et al., 2019) where they use ten datasets to predict temperatures from different weather attributes
133 using those techniques. From the experiments, they obtain a root mean square error less than 0.6°C .

134 **3. kNN-RegID: A technique for regression from imprecise data based on k -nearest neighbors**

135 The k -nearest neighbors technique is widely used in data mining. The technique can be applied to high-dimensionality
136 problems where the attributes describing the instances can be both nominal and numerical. In addition, k -nearest
137 neighbors has been successfully applied in solving both the regression and classification tasks in a variety of fields.
138 In literature there are proposals for studies based on k -nearest neighbors where some of them are framed in the Fuzzy
139 Set Theory to incorporate imprecision therein. On the one hand, some proposals incorporate imprecision in the class
140 attribute (Keller et al., 1985). From that imprecision, several works were developed that focus on obtaining the final
141 membership degrees of the different classes (Han and Kim, 1999). On the other hand, there are other works focus on
142 the calculation of distances (Mitchell and Schaefer, 2001).

143 In this manuscript, a regression technique based on k -nearest neighbors that supports datasets with imprecise values
144 is proposed. Specifically, the k -nearest neighbors technique is used in order to deal with data whose attribute values
145 are defined from membership functions. This technique is denoted by kNN-RegID and is described below.

146 *3.1. Description of the kNN-RegID technique*

147 The kNN-RegID technique allows the imputation of missing values for numerical domain attributes from imprecise
148 data. These imprecise input data can be both nominal and numerical. In order to homogenize the structure of the input
149 data, the technique works with attribute values described by tuples. Each tuple is formed by elements of the form

150 $\{\mu_i/v_i\}$ where v_i is a domain value of the attribute i and $\mu_i \in [0, 1]$ the membership degrees of those values. This
 151 representation by means of tuples allows us to formulate:

- 152 • Trapezoidal and triangular fuzzy values, missing values, interval values and crisp values for numerical attributes.
 153 The values of these attributes are represented by tuples in the form $[\mu_1/v_1, \mu_2/v_2, \mu_3/v_3, \mu_4/v_4]$.
- 154 • Fuzzy subsets, missing values and crisp values for nominal attributes. In these cases, the values of these at-
 155 tributes are represented by $\{\mu_1/v_1, \mu_2/v_2, \mu_3/v_3, \dots\}$, with as many μ/v pairs as necessary to indicate the at-
 156 tribute value.

157 Therefore, the input datasets to the kNN-RegID technique are composed of instances with attributes defined as
 158 indicated above. In general, each instance $\mathbf{q} = (q_1, q_2, \dots, q_{n-1}, q_n)$ is made up of n attributes where the attributes q_i ,
 159 $i = 1, \dots, n-1$ are described by tuples and the attribute to estimate q_n is always given by a crisp value described by a
 160 tuple $\{1/v_i\}$ or only as v_i . The operation of the kNN-RegID technique is defined in the Algorithm 1.

Algorithm 1: kNN-RegID - k -Nearest Neighbors for regression from imprecise data

Input Dataset D , instance to infer \mathbf{q} , value k ($1 \leq k \leq |D|$), value U_E ($U_E \in [0, 1]$), similarity (dissimilarity) function $S(\cdot, \cdot)$,
 entropy function $f_e(\cdot)$
 Obtain the set of k instances of D (denoted by K_S) more/less similar/dissimilar to \mathbf{q} according to the $S(\cdot, \cdot)$ function.
 Calculate $f_e(\mathbf{q}')$, $\forall \mathbf{q}' \in K_S$ and $E_{K_S} = \frac{\sum_{\mathbf{q}' \in K_S} f_e(\mathbf{q}')}{|K_S|}$
if ($E_{K_S} \leq U_E$) **then**
 if similarity **then** $q_n = \sum_{\mathbf{q}' \in K_S} (1 - f_e(\mathbf{q}')) \cdot S(\mathbf{q}, \mathbf{q}') \cdot q'_n$
 if dissimilarity **then** $q_n = \sum_{\mathbf{q}' \in K_S} (1 - f_e(\mathbf{q}')) \cdot (1 - S(\mathbf{q}, \mathbf{q}')) \cdot q'_n$
 Output q_n
else
 Output Estimation is not performed
end if

161 In general, in the technique k -nearest neighbors plays a very important role the function used to obtain the set of
 162 k -nearest neighbors to a given instance. Since kNN-RegID is going to handle imprecise attribute values, the function
 163 is defined for this type of values. When the set K_S is formed by the k examples more similar to a given one it is
 164 considered fuzzy similarity functions and when the set K_S is composed by the k examples with less dissimilarity value
 165 it is considered a fuzzy dissimilarity function. In general, the function used to obtain K_S is defined as $S(\mathbf{q}, \mathbf{q}') =$
 166 $\sum_{i=1}^{n-1} \frac{S_t(q_i, q'_i)}{n-1}$ where $t = 1$ indicates a similarity/dissimilarity function defined over imprecise numerical attributes and
 167 $t = 2$ indicates a similarity/dissimilarity function defined for imprecise nominal attributes.

168 When working with imprecise data, the kNN-RegID technique uses a measure of the imprecision of the different
 169 attribute values. With this measurement, the technique can take into account that those less imprecise instances have a
 170 greater relevance in the estimates made. Fuzziness measures or fuzzy entropy functions ($f_e(\cdot)$) are used because they
 171 allow to measure the indefiniteness described by the memberships function of fuzzy sets. In general, the imprecision
 172 of an instance is measured as $f_e(\mathbf{q}') = \frac{\sum_{i=1}^{n-1} f_e(q'_i)}{n-1}$. In addition, the technique incorporates the parameter $U_E \in [0, 1]$ that
 173 establishes a limit of imprecision for the set of neighbors from which an estimation is performed. If the imprecision
 174 of the set K_S , denoted by E_{K_S} , exceeds this threshold, the estimation is not carried out.

175 The q_n value is obtained by averaging the q'_n values of the neighbors in K_S . In this average, the value of each
176 neighbor is applied weighted by two values: the value of similarity/dissimilarity of each \mathbf{q}' with \mathbf{q} and its imprecision
177 $f_e(\mathbf{q}')$, in order that the more-similar/less-dissimilar to \mathbf{q} and less is its imprecision, the greater is its contribution in
178 the final result. This is reflected in the Algorithm 1 with the factors $1 - f_e(\mathbf{q}')$, and $S(\mathbf{q}, \mathbf{q}')$ or $1 - S(\mathbf{q}, \mathbf{q}')$ depending
179 on whether the $S(\cdot, \cdot)$ function is similarity/dissimilarity, respectively.

180 **4. Datasets, techniques, evaluation and validation of experiments.**

181 *4.1. Information collection and data preparation*

182 *4.1.1. Study areas in south-east Spain*

183 The Murcian Institute of Agricultural and Food Research and Development, among other things, collects informa-
184 tion on the weatherology of different areas through the Agricultural Information Service of Murcia Region (SIAM,
185 <http://siam.imida.es>). The covered areas, and municipalities that integrates, are the following:

- 186 • Altiplano – Yecla, Jumilla, Abanilla and Fortuna.
- 187 • Noroeste – Moratalla, Caravaca de la Cruz, Cehegín and Bullas.
- 188 • Río Mula – Mula, Pliego, Albudeite and Campos del Río.
- 189 • Vega del Segura – Murcia, Beniel, Santomera, Alcantarilla, Molina de Segura, Torres de Cotillas, Alguazas,
190 Ceutí, Lorquí, Archena, Ulea, Villanueva del Segura, Ojós, Ricote, Blanca, Abarán, Cieza and Calasparra.
- 191 • Valle del Guadalentín – Lorca, Puerto Lumbreras, Águilas, Mazarrón, Totana, Aledo, Alhama de Murcia and
192 Librilla.
- 193 • Campo de Cartagena – Fuente Álamo, Cartagena, Unión (La), Torre Pacheco, San Javier, San Pedro del Pinatar
194 and Alcázares (Los).

195 In (Martínez-Núñez et al., 2015), it is described that in the areas of the Altiplano, Noroeste, Río Mula and north
196 of the Vega del Segura, the average percentage of frost occurring is between 80% and 100%. And the average date of
197 the first frost starts from 1 to 15 December, and the last frost is until 31 March. For our study we have selected, from
198 these regions, 5 weather stations that are shown in the Table 1. These stations are surrounded by stone fruit crops and
199 therefore the results obtained are interesting to prevent frost on these crops.

200 *4.1.2. Initial collection of information. Initial data*

201 Each station is equipped with the following sensors and ephemeris: weather vane, radiometer, rain gauge, data-
202 logger and thermo-hygrometer. The information collected corresponds to 7 years (2012-2018). The initial time series
203 data obtained from SIAM sensors correspond to values obtained every 5 minutes. These are grouped 12 by 12 to show
204 only values for each hour. For this reason, some of the measurements show the minimum, average and maximum
205 values for each hour. The type of information obtained is shown in the Table 2.

Table 1: Description of the weather stations in study and places by hours of cold ($\leq 7^\circ$) per year of the Region of Murcia, Spain.

Caravaca – Noroeste Station CR12 – Altitude 869m Coordinate: $38^\circ 2' 38.24'' - 1^\circ 58' 48.67''$
Cehegín – Noroeste Station CR32 – Altitude 433m Coordinate: $38^\circ 6' 39'' - 1^\circ 19' 27.58''$
Calasparra – Vega del Segura Station CI52 – Altitude 275m Coordinate: $38^\circ 15' 12.59'' - 1^\circ 41' 41.89''$
Jumilla – Altiplano Station JU71 – Altitude 401m Coordinate: $38^\circ 23' 40.01'' - 1^\circ 14' 21.58''$
Jumilla – Altiplano Station JU81 – Altitude 341m Coordinate: $38^\circ 19' 11.3'' - 1^\circ 19' 27.58''$

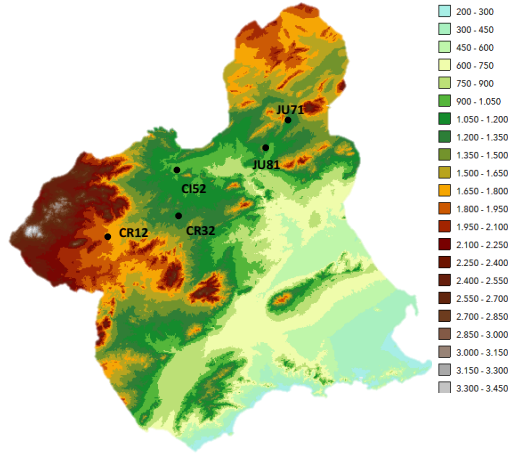


Table 2: Information collected every hour for each station.

Weather station code	Date of data reading
Hour of data reading	Min. relative humidity (%)
Mean relative humidity (%)	Max. relative humidity (%)
Mean radiation (W/m^2)	Max. radiation (W/m^2)
Accumulated radiation (W/m^2)	Mean wind speed (m/s)
Max. wind speed (m/s)	Mean wind direction ($^\circ C$)
Rainfall (mm)	Dew point ($^\circ C$)
Vapor pressure deficit (kPa)	Min. temperature ($^\circ C$)
Mean temperature ($^\circ C$)	Max. temperature ($^\circ C$)

206 *4.1.3. Preprocessing of information*

207 After the collection of information from the five weather stations, a data preprocessing process is carried out to
 208 generate the time series datasets. These datasets are used to obtain the classification and regression models of the
 209 decision support system.

210 *Building the time series dataset to regression.* From the initial data, the following preprocessing of the information is
 211 performed to construct the time series dataset to regression.

212 1. Attribute construction:

In the Table 3 the constructed attributes are shown.

Table 3: Extended Attribute Description.

Attrib.	Description	Attrib.	Description
Stat	Wheather station code	Date	Date of data reading
H	Hour of data reading	RH _f	Relative humidity
R _f	Radiation	AR	Accumulated radiation
WS _f	Wind speed	WD	Mean wind direction
RF	Rainfall	DE	Dew point
VPD	Vapor pressure deficit	T _f	Temperature

213

214 These attributes include RH_f, R_f, WS_f and T_f which take fuzzy values. These fuzzy attributes are constructed
 215 as follows:

- 216 • From the weather attributes that have minimum, mean and maximum values (specifically, the “relative
 217 humidity” and “temperature” measures) fuzzy values are constructed. These values are trapezoidal fuzzy
 218 numbers (Figure 1a and 1b) given by $[\mu_1/v_1, \mu_2/v_2, \mu_3/v_3, \mu_4/v_4]$ where $\frac{v_2+v_3}{2} = mean_{value}$ with $\mu_2 = \mu_3 =$
 219 1 ; if $(max_{value} - mean_{value} \leq mean_{value} - min_{value})$ then $v_4 = max_{value}$ with $\mu_4 = 0$ and $v_1 = min_{value}$ with
 220 $\mu_1 = \frac{x-v_1}{v_2-v_1}$, else $v_1 = min_{value}$ with $\mu_1 = 0$ and $v_4 = max_{value}$ with $\mu_4 = \frac{v_4-x}{v_4-v_3}$. If the min_{value} or max_{value}
 221 are lower or higher, respectively, than the minimum or maximum global values, they will be defined by
 222 the global minimum and maximum.
- 223 • From the weather attributes that have mean and maximum values (specifically, the “radiation” and “wind
 224 speed” measures) fuzzy values are constructed. These values are trapezoidal fuzzy numbers (Figure 1c)
 225 given by $[\mu_1/v_1, \mu_2/v_2, \mu_3/v_3, \mu_4/v_4]$ where $\frac{v_2+v_3}{2} = mean_{value}$, $v_4 = max_{value}$ with $\mu_4 = 0$ and $v_1 = 2 \times$
 226 $mean_{value} - max_{value}$ with $\mu_1 = \frac{x-v_1}{v_2-v_1}$. If the min_{value} is less than the global minimum value, the value will
 227 be the global minimum value.
- 228 • The values of the measures corresponding to the missing values have been maintained. In these cases,
 229 the constructed attributes will contain trapezoidal fuzzy numbers $[\mu_1/v_1, \mu_2/v_2, \mu_3/v_3, \mu_4/v_4]$ where $v_1 =$
 230 $v_2 = min_{global}$ with $\mu_1 = \mu_2 = 1$ and $v_3 = v_4 = max_{global}$ with $\mu_3 = \mu_4 = 1$ (Figure 1d).

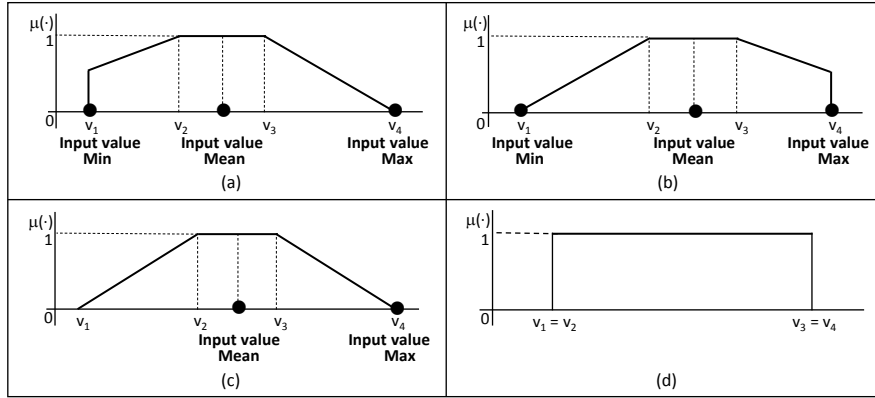


Figure 1: Representations of fuzzy values constructed from the known values minimum, mean, maximum and missing of a measure.

- 231 2. Instance construction. From the attributes in Table 3, the instances are formed as follows: The first nine attributes
 232 correspond to the values of RH_f , R_f , AR , WS_f , WD , RF , DE , VPD and T_f taken in the hour $H - 1$; the
 233 following nine attributes correspond to the values of the same previous attributes but taken at H and the last
 234 attribute (attribute to be inferred) corresponds to the value of the minimum temperature during the hour $H + 1$.
 235 Therefore, each instance will be composed of 19 attributes as shown in the Table 4.

Table 4: Constructed Instance.

H-1									H									H+1
RH_f	R_f	AR	WS_f	WD	RF	DE	VPD	T_f	RH_f	R_f	AR	WS_f	WD	RF	DE	VPD	T_f	T_{MIN}

- 236 3. The instances are filtered selecting only those that have the value $T_{MIN} \leq 7^\circ C$.

237 *Building the time series dataset for classification.* This dataset is constructed from the dataset already built for regres-
 238 sion. Now, a new attribute is built, which is denoted by $CLASS_{FnF}$, with two possible values: Frost or NoFrost. For
 239 each instance, and using the value $v_{T_{MIN}}$ of the T_{MIN} attribute, the value for $CLASS_{FnF}$ is defined as:

- 240 • If $v_{T_{MIN}} > 0$ then $CLASS_{FnF} = \text{NoFrost}$, else $CLASS_{FnF} = \text{Frost}$

241 From dataset for regression, removing its T_{MIN} attribute and adding the new one $CLASS_{FnF}$, the dataset for
 242 classification is obtained.

243 4.1.4. Features of constructed datasets

244 Through the preprocessing and construction process, 10 datasets are obtained (5 for classification and 5 for regres-
 245 sion) corresponding to the 5 stations (two datasets per station). The features of the 10 datasets are shown in Table
 246 5. For each station, it is shown the number of instances, the total number attributes, the number of numerical and
 247 nominal attributes without taking into account the attribute to be inferred (that in classification will be nominal and
 248 in regression will be numerical), the number of classes for the attribute to be inferred in classification, the number of
 249 missing values, the number of fuzzy values and the number of instances with imprecise values (missing and/or fuzzy
 250 values). The last three values are expressed in percentage.

Table 5: Features of the datasets for the different stations, where $|D|$ - number of instances, Attr - number of attributes, Nu and No - number of numerical and nominal attributes, respectively, I - number of classes, NMV - number of missing values, NFV - number of fuzzy values and NI-MFV - number of instances with imprecise values.

Acron	$ D $	Attr	Nu	No	I	%NMV	%NFV	%NI-MFV
CR12	15185	22	18	3	2	0.020	44.4	100
CR32	11855	22	18	3	2	0.010	44.4	100
CI52	9094	22	18	3	2	0.023	44.4	100
JU71	8470	22	18	3	2	0.001	44.4	100
JU81	8296	22	18	3	2	0.010	44.4	100

251 4.2. Techniques used and their configuration

252 The technique proposed in Section 3 is used for the regression process and to infer the temperature value. In ad-
 253 dition, two classification techniques proposed in the literature are also applied. Specifically, the decision tree “FDT_{ii}”
 254 (Cadenas et al., 2012) and k -nearest neighbors “kNN_{imp}” (Cadenas et al., 2018) techniques, which support imprecise
 255 data, are applied.

256 First, the techniques used for classification FDT_{ii} and kNN_{imp} are briefly described. Then, the configurations used
 257 in the three techniques in the different experiments are detailed.

258 4.2.1. Brief description of techniques FDT_{ii} and kNN_{imp} used for classification

259 *FDT_{ii}: a fuzzy decision tree for classification.* The FDT_{ii} technique (Cadenas et al., 2012) is a fuzzy decision tree
 260 that can classify instances that contain imprecise values in their input attributes. This technique needs a fuzzy/crisp
 261 discretization of the numerical attributes that are part of the problem. In order to handle imprecise values and to be
 262 able to obtain in each node the best input attribute to split it, the technique uses a similarity function to measure how
 263 similar a fuzzy value is with the labels of a partition.

264 Using this similarity function each instance descends for each branch of the tree with a weight. The class value
 265 provided for the tree to classify a new instance \mathbf{q} is determined by the majority class of the tree leaf reached for \mathbf{q} with
 266 greater weight. For more details on this technique, refer to the paper (Cadenas et al., 2012).

267 *kNN_{imp}*: *k-nearest neighbors for classification*. The kNN_{imp} technique (Cadenas et al., 2018) is based on k -nearest
 268 neighbors and allows to classify instances from imprecise data. In addition, it provides class values that may be
 269 also expressed with imprecise values when there is no class value clearly highlighted from the others in the resulting
 270 classification. The vague concept “clearly highlighted” can be defined by the external parameter U_D of the technique.

271 kNN_{imp} technique has several aggregation methods of the information provided by the k -nearest neighbors to
 272 decide the classification (Cadenas et al., 2018). These methods provide high flexibility to the technique, allowing
 273 choose them according to the classification problem. Two of them are used in this work: WM_{sv} and WM_{cv} .

274 The kNN_{imp} technique with the WM_{sv} method assigns to q a crisp subset $\{1/\omega_h\}$ composed of ω_h defined as
 275 $h = \arg \max_{c=1, \dots, I} \sum_{j=1}^k \mu_{q_n^j}(\omega_c) \cdot S(\mathbf{q}^j, \mathbf{q}) \cdot (1 - f_e(\mathbf{q}^j))$ where $(\mu_{q_n^j}(\omega_c) \cdot S(\mathbf{q}^j, \mathbf{q}) \cdot (1 - f_e(\mathbf{q}^j)))$ returns the score assigned by
 276 a neighbor q^j to each class value $c = 1, \dots, I$, determined by the weight of that value in q_n^j ($\mu_{q_n^j}(\omega_c)$), by the weight of
 277 \mathbf{q}^j according to its nearness $S(\mathbf{q}^j, \mathbf{q})$ when $S(\cdot, \cdot)$ is a similarity function (or $1 - S(\mathbf{q}^j, \mathbf{q})$ when $S(\cdot, \cdot)$ is a dissimilarity
 278 function) and by the weight of \mathbf{q}^j according to its imprecision ($(1 - f_e(\mathbf{q}^j))$).

279 While the kNN_{imp} technique with the WM_{cv} method returns as output a fuzzy subset $\{\mu(\omega_t)/\omega_t\}$ composed of the

280 class values ω_t with $\mu(\omega_t) > 0$ defined as
$$\mu(\omega_t) = \frac{\sum_{j=1}^k \mu_{q_n^j}(\omega_t) \cdot S(\mathbf{q}^j, \mathbf{q}) \cdot (1 - f_e(\mathbf{q}^j))}{\sum_{j=1}^k \sum_{c=1}^I \mu_{q_n^j}(\omega_c) \cdot S(\mathbf{q}^j, \mathbf{q}) \cdot (1 - f_e(\mathbf{q}^j))}$$

281 For further details on this technique, refer to the paper (Cadenas et al., 2018).

282 4.2.2. Configuration of techniques for experiments

283 In this subsection, the different values assigned to the parameters of the used techniques are detailed.

284 To kNN -RegID technique: A value of $U_E=1$ has been used. With respect to the value of k , in each test the value
 285 of k that obtains the best results has been selected and indicated in the test. In addition, the following functions have
 286 been used:

- 287 • For numerical attributes, S_1 function is the similarity function defined in (Dengfeng and Chuntian, 2002):

$$S_1(q_i, q'_i) = 1 - \frac{\frac{|v_1 - v'_1| + |v_2 - v'_2| + |v_3 - v'_3| + |v_4 - v'_4|}{4}}{\max_i - \min_i} \quad (1)$$

288 where q_i and q'_i are values for the numerical attribute i expressed by means of tuples.

- 289 • For nominal attributes, S_2 function is the similarity function based on the Minkowski r -metric (Beckenbach and
 290 Bellman, 1961):

$$S_2(q_i, q'_i) = 1 - \frac{\sum_{j=1}^{|\Omega_i|} |\mu_{q_i}(v_j) - \mu_{q'_i}(v_j)|}{|\Omega_i|} \quad (2)$$

291 where $|\Omega_i|$ is the cardinal of the domain of the nominal attribute i and q_i and q'_i are values for the nominal
 292 attribute i expressed by means of the tuples commented previously.

293 • The entropy function $f_e(\cdot)$ used is the one defined by Luca and Termini in (de Luca and Termini, 1972):

$$f_e(q_i) = \begin{cases} \frac{1}{|\Omega_{q_i}|} \sum_{v \in q_i} \mu_{q_i}(v) & \text{if } q_i \text{ has an imprecise value} \\ 0 & \text{other case} \end{cases} \quad (3)$$

294 To FDT_{ii} technique: The stop condition of the fuzzy decision tree is double: if a node contains at least 95% of
 295 instances of the same class, the node is labeled as a leaf; if the number of instances of the node is smaller than 2.5%
 296 of the dataset size (M), the node is labeled as a leaf node.

297 To kNN_{imp} technique with the WM_{sv} and WM_{cv} aggregation methods: The $S(\cdot, \cdot)$ and $f_e(\cdot)$ functions are those
 298 described in (1), (2) and (3). $U_D=0.2$ has been used. Regarding to the k value, in each test the value that obtains the
 299 best results has been selected, indicating this value in the several tables.

300 4.3. Measures used to assess results. Validating experiments

301 For all experiments, a 5-fold cross-validation is performed. In addition, an evaluation with complete training
 302 dataset is carried out.

303 For the classification task:

- 304 • Given a confusion matrix obtained by a classification technique, the different used measures are as follows: ACC
 305 (accuracy) = $\frac{TP+FN}{TP+TN+FP+FN}$; TPR (sensitivity) = $\frac{TP}{TP+FN}$; TNR (specificity) = $\frac{TN}{TN+FP}$; and F-score (harmonic
 306 mean of sensitivity and precision) = $\frac{2TP}{2TP+FP+FN}$, where TP: forecasted frost, FP: forecasted false frost, FN:
 307 frost not predicted, TN: no frost. The values of these measurements range from 0 to 1, and when the values are
 308 close to 1, they indicate good model results.
- 309 • To determine the economic impact of the decisions taken, the cost matrix is used. This matrix indicates the
 310 estimated cost to protect crops and the estimated cost of losing the crop to frost. The value of the classification
 311 cost is estimated by the expression $E=\alpha \cdot FP + \beta \cdot FN$ where α is the cost of protecting the crop and β is the
 312 estimated cost for the loss of the crop. As a particular case, for the experiments $\alpha = 1$ and $\beta = 10$ are used.
- 313 • Due to the possibility that the kNN_{imp} technique obtains an imprecise classification, the confusion matrix must
 be extended (Table 6).

Table 6: Extended confusion matrix.

	Frost	NoFrost	{Frost,NoFrost}	← classified as
Frost	TP	FN	TP_FN	
NoFrost	FP	TN	FP_TN	

314

315 As shown the extended confusion matrix, a new value appears in the prediction {Frost,NoFrost} for CLASS_{FN}.
 316 This new value appears when the technique has obtained for each class value its membership degree $\{\mu_1/\text{Frost}\}$
 317 and $\{\mu_2/\text{NoFrost}\}$ verifying that $\frac{|\mu_1-\mu_2|}{\max(\mu_1,\mu_2)} \leq U_D$. In this situation, the technique does not know which class
 318 value to choose and classify the instance with {Frost,NoFrost}. With these new values, and in a real situation,

the user is the one who must make a decision about it. For the experiments, we make a conservative decision (the lowest cost class), deciding that:

- If the inferred class is imprecise {Frost,NoFrost}, we will decide that the instance is of the Frost class. This decision reflects that we believe that a frost may occur and we apply the actions to try to reduce its impact. Therefore, the classifications {Frost,NoFrost} will be taken as Frost and in the extended confusion matrix we will have that TP_FN will be successes and FP_TN failures.

The different versions of kNN_{imp} technique will be denoted as kNN_{imp}^C and kNN_{imp}^F , depending on whether it is used the aggregation method WM_{sv} that produces crisp outputs or the WM_{cv} method that produces fuzzy outputs, respectively. To denote the conservative decision from the technique kNN_{imp}^F , kNN_{imp}^{Fcons} will be used.

For the regression task:

- $MSE(X, Y)$ (mean square error) = $\frac{1}{n} \sum_{i=1}^n (X_i - Y_i)^2$ and $MAE(X, Y)$ (mean absolute error) = $\frac{1}{n} \sum_{i=1}^n |X_i - Y_i|$.
- $CC(X, Y)$ (Pearson correlation coefficient) = $\frac{Cov(X, Y)}{\sigma_X \sigma_Y}$ where Cov is the covariance and σ is the standard deviation.
- $R^2(X, Y)$ (determination coefficient) = $1 - \frac{\sum_{i=1}^n (X_i - Y_i)^2}{\sum_{i=1}^n (X_i - \bar{X})^2}$ where \bar{X} is the mean of the real data.

Finally, and to check which technique has the best overall behavior, a statistical analysis is performed. To perform this analysis, non-parametric statistical tests are applied, (García et al., 2010). The Wilcoxon signed-rank test is used to perform pairwise comparison between two techniques. The Friedman test is used to analyze if there are significant differences in the behavior of the different techniques. If the null hypothesis is rejected, this indicates that there are differences between the techniques, although it does not indicate which technique or techniques are better. In order to identify which of the techniques has the best behaviour, a post hoc test is carried out. As a post hoc test, Holm's procedure is used. For this statistical analysis, the R package (Ihaka and Gentleman, 1996) is used.

5. Results and discussions

In this section, and in order to answer the different questions posed, a series of experiments with the different techniques and datasets are going to be conducted.

First, the relationship between temperature and the other weather attributes (of the current time and the previous one) is studied in order to predict a frost, and to infer the temperature value for the next hour. To achieve this target, the FDT_{ii} technique is applied to the dataset for classification using a 5-fold cross-validation. Once the model parameters have been validated using cross-validation, the model is obtained using the complete dataset and the information provided is analyzed in order to select the most relevant attributes for the decision system.

Secondly, an adjustment, selection and validation of the models that will be incorporated into the decision system is performed. For this purpose, the kNN_{imp} technique is applied to the dataset for classification, with and without selected attributes, using a 5-fold cross-validation. After performing a statistical analysis of the results, the classification model is obtained, which is incorporated into the decision system.

351 In addition, the kNN-RegID technique is applied to the dataset for regression, with and without selected attributes,
 352 using a 5-fold cross-validation and after performing a statistical analysis of the results obtained, the regression model
 353 is obtained and incorporated into the decision system.

354 5.1. Applying FDT_{ii} technique: Characterization of the problem from the datasets for classification

355 Using the datasets for classification and the different models provided by FDT_{ii} technique, certain characteristic
 356 elements for the detection of frost from weather attributes previously measured in certain geographical areas are
 357 obtained. For this purpose, FDT_{ii} technique is applied to the dataset for the different stations using a cross-validation
 358 and training. In the Table 7, the results obtained for the different measures are shown.

Table 7: Results in % of a 5-fold cross-validation and training obtained with the FDT_{ii} technique and datasets for classification (in subscript the standard deviation is shown). The M values obtaining these results for the different stations are as follows: 380, 296, 227, 212 and 207, respectively.

		CR12	CR32	CI52	JU71	JU81	mean
5cv	ACC	95.19 _{0.3}	95.31 _{0.4}	96.82 _{0.2}	96.10 _{0.2}	97.60 _{0.3}	96.20 _{0.3}
	TPR	83.28 _{1.0}	90.51 _{1.2}	88.47 _{1.7}	85.66 _{2.1}	88.37 _{2.4}	87.26 _{1.7}
	TNR	97.61 _{0.2}	97.08 _{0.3}	98.30 _{0.3}	97.86 _{0.4}	98.74 _{0.1}	97.92 _{0.3}
	F-score	85.40 _{0.6}	91.25 _{1.0}	89.23 _{0.7}	86.36 _{0.5}	88.96 _{1.4}	88.24 _{0.8}
	E	918.2 _{77.3}	658.4 _{57.5}	340.4 _{51.1}	381.0 _{51.6}	230.6 _{46.6}	505.7 _{56.8}
training	ACC	95.19	96.81	96.83	96.81	97.65	96.66
	TPR	82.68	89.02	87.40	89.02	86.70	86.96
	TNR	97.73	98.18	98.49	98.18	99.00	98.32
	F-score	85.29	89.28	89.17	89.28	89.00	88.40
	E	4727	1631	1827	1631	1284	2220

359 From the models obtained by train, the prediction of the classes Frost and NoFrost can be characterized because
 360 these models use a subset of the attributes. The attributes used by the different classification models for the different
 361 stations are as follows:

- 362 • CR12 station – The model uses 7 attributes: DE^{H-1} , R_f^H , AR^H , WS_f^H , DE^H , VPD^H , T_f^H .
- 363 • CR32 station – The model uses 7 attributes: VPD^{H-1} , R_f^H , AR^H , WD^H , DE^H , VPD^H , T_f^H .
- 364 • CI52 station – The model uses 5 attributes: VPD^{H-1} , R_f^H , AR^H , WD^H , T_f^H .
- 365 • JU71 station – The model uses 5 attributes: DE^{H-1} , VPD^{H-1} , R_f^H , AR^H , T_f^H .
- 366 • JU81 station – The model uses 6 attributes: RH_f^{H-1} , VPD^{H-1} , T_f^{H-1} , R_f^H , AR^H , T_f^H .

367 5.1.1. Analyzing the information and characterizing the problem

368 According to the different models learned through the FDT_{ii} technique for the different stations, some conclusions
 369 referring to the weather conditions and the terrain orography that condition the occurrence of a frost are obtained.

370 First of all, it is important to emphasize that of the attributes selected and indicated above, and according to the
 371 models obtained, there is a subset of them that mainly characterize the Frost class. In general, the most relevant
 372 attributes are radiation, accumulated radiation and temperature. These three attributes appear in the first and second
 373 level of all the models being therefore the ones that better discriminate the instances labeled with Frost from those of

374 NoFrost. In all stations, and when the current temperature values are negative but close to 0 (values around $[-2.0^{\circ}\text{C}, -$
375 $0.5^{\circ}\text{C}]$), the prediction of a frost depends on the values of radiation (less than $70\text{w}/\text{m}^2$) and accumulated radiation (less
376 than $0.25\text{w}/\text{m}^2$).

377 When the temperature values are at $[-1.0^{\circ}\text{C}, 2.0^{\circ}\text{C}]$, it is when the other attributes are involved for the prediction
378 of the label Frost. Specifically, and knowing that the stations JU71 and JU81 belong to the region of the “Altiplano”
379 and present an orography of flatlands and mountains; that the stations CR12 and CR32 belong to the region of the
380 “Noroeste”, emphasizing the station CR12 for being located in the most mountainous zone and of greater altitude;
381 and finally that, the station CI52 belongs to the “Vega del Segura” and is the one of lower altitude, the conclusions
382 obtained are the following ones:

- 383 • The models indicate that in the region of the “Altiplano” the wind measure does not influence in the prediction
384 of a frost. In the area of the JU71 station, when the temperature is at $[-1.0^{\circ}\text{C}, 1.0^{\circ}\text{C}]$, a frost is predicted for
385 the next hour when the radiation is very low (less than $1.0\text{w}/\text{m}^2$) and the dew point of the previous hour is at
386 $[-24.0^{\circ}\text{C}, -2.96^{\circ}\text{C}]$. In the area of the JU81 station, and when the temperature is at $[-1.0^{\circ}\text{C}, 1.0^{\circ}\text{C}]$, a frost is
387 predicted for the next hour when the radiation is very low (less than $0.1\text{w}/\text{m}^2$).
- 388 • The “Noroeste” region is the highest. In the less mountainous area (mountains and valleys around the CR32
389 station), there is an influence of the wind direction for the prediction of a frost when the radiation is low (less
390 than $0.13\text{w}/\text{m}^2$). On the one hand, if the temperature is at $[0.5^{\circ}\text{C}, 2.0^{\circ}\text{C}]$ and the radiation is low (less than
391 $0.13\text{w}/\text{m}^2$) a frost is predicted when dew point is less than -3.5°C ; and when dew point is at $[-3.5^{\circ}\text{C}, 1.0^{\circ}\text{C}]$,
392 a frost is predicted when the wind direction is south/southwest. On the other hand, if the temperature is at
393 $[-1.0^{\circ}\text{C}, 1.0^{\circ}\text{C}]$ and the radiation is low (less than $0.13\text{w}/\text{m}^2$), a frost occurs when the direction of the wind is
394 not south/southwest; or if the direction is south/southwest but the dew point is at $[-22.0^{\circ}\text{C}, 4.0^{\circ}\text{C}]$.
- 395 However, in the more mountainous areas (around CR12), there is an influence of wind speed (light wind, less
396 than $8\text{m}/\text{s}$), low dew point (at $[-22.0^{\circ}\text{C}, 4.0^{\circ}\text{C}]$) and low radiation (less than $3.7\text{w}/\text{m}^2$) in the prediction of a frost.
- 397 • In the region of the “Vega del Segura” also has an influence the wind direction in the prediction of a frost. When
398 the temperature is at $[-1.0^{\circ}\text{C}, 1.0^{\circ}\text{C}]$ and the radiation is low (less than $0.1\text{w}/\text{m}^2$), a frost is predicted when the
399 wind direction is from the north/northeast, or if the wind direction is not from the north/northeast, a frost is
400 predicted if the vapor pressure deficit is low (this at $[0.0\text{kPa}, 1.7\text{kPa}]$).

401 5.2. Applying the $k\text{NN}_{\text{imp}}$ technique: Selecting a classifier

402 5.2.1. Using datasets for classification

403 In this section the executions of the $k\text{NN}_{\text{imp}}$ technique with the datasets for classification for the different stations
404 are displayed. Table 8 shows the results obtained for the different assessment measures by the $k\text{NN}_{\text{imp}}^{\text{C}}$, $k\text{NN}_{\text{imp}}^{\text{F}}$ and
405 $k\text{NN}_{\text{imp}}^{\text{Fcons}}$ techniques when a 5-fold cross-validation is used.

406 As it can be seen in Table 8, the cost of wrong classification obtained by the $k\text{NN}_{\text{imp}}^{\text{Fcons}}$ technique has improved
407 significantly with respect to those obtained by the $k\text{NN}_{\text{imp}}^{\text{C}}$ technique.

Table 8: Results in % of a 5-fold cross-validation (subscripts show standard deviation). For each station and measure, the results obtained by kNN_{imp}^C , kNN_{imp}^F and kNN_{imp}^{Fcons} techniques are shown, respectively. Values of k used are 7, 9, 5, 17 and 7 (in kNN_{imp}^C) and 11, 9, 7, 13 and 11 (in kNN_{imp}^F and kNN_{imp}^{Fcons}) for each station respectively.

	CR12	CR32	CI52	JU71	JU81	mean
ACC	95.20 _{0.3}	95.30 _{0.3}	96.62 _{0.2}	95.80 _{0.6}	97.16 _{0.4}	96.02 _{0.4}
	[93.7 _{0.6} ,96.3 _{0.5}]	[94.4 _{0.3} ,95.9 _{0.3}]	[95.7 _{0.3} ,97.1 _{0.1}]	[94.4 _{0.4} ,96.7 _{0.4}]	[95.9 _{0.4} ,98.1 _{0.2}]	[94.9 _{0.4} ,96.8 _{0.3}]
	95.13 _{0.3}	95.20 _{0.4}	96.39 _{0.2}	95.51 _{0.4}	96.94 _{0.3}	95.83 _{0.3}
TPR	84.23 _{1.3}	91.54 _{1.1}	88.98 _{1.1}	83.98 _{1.8}	89.03 _{1.3}	87.55 _{1.3}
	[78.9 _{1.8} ,87.2 _{1.7}]	[89.5 _{0.7} ,92.4 _{0.9}]	[85.9 _{1.1} ,90.2 _{1.4}]	[79.2 _{2.1} ,86.8 _{1.2}]	[82.7 _{1.5} ,91.9 _{1.4}]	[83.2 _{1.4} ,89.7 _{1.3}]
	87.15 _{1.7}	92.35 _{0.9}	90.24 _{1.4}	86.77 _{1.2}	91.83 _{2.2}	89.67 _{1.5}
TNR	97.43 _{0.3}	96.69 _{0.3}	97.96 _{0.3}	97.79 _{0.5}	98.16 _{0.3}	97.61 _{0.3}
	[96.8 _{0.2} ,98.1 _{0.3}]	[96.3 _{0.5} ,97.2 _{0.3}]	[97.5 _{0.3} ,98.3 _{0.2}]	[97.0 _{0.4} ,98.4 _{0.4}]	[97.6 _{0.3} ,98.8 _{0.3}]	[97.0 _{0.3} ,98.2 _{0.3}]
	97.70 _{0.8}	96.25 _{0.5}	97.47 _{0.3}	96.99 _{0.4}	97.58 _{0.3}	97.20 _{0.5}
F-score	85.55 _{0.7}	91.33 _{0.9}	88.67 _{1.0}	85.24 _{1.5}	87.30 _{1.5}	87.62 _{1.1}
	[81.0 _{1.0} ,88.8 _{1.0}]	[89.7 _{0.8} ,92.3 _{0.9}]	[85.7 _{1.2} ,90.3 _{1.1}]	[80.4 _{0.8} ,88.4 _{1.0}]	[81.7 _{1.7} ,91.3 _{0.8}]	[83.7 _{1.1} ,90.2 _{1.0}]
	85.79 _{0.5}	91.23 _{1.0}	88.12 _{1.2}	84.81 _{1.0}	86.82 _{1.0}	87.35 _{0.9}
E	874.8 _{87.7}	599.2 _{49.8}	329.6 _{24.2}	424 _{58.7}	227.2 _{30.8}	491 _{50.2}
	[709 _{111.6} ,1168 _{133.6}]	[539 _{43.1} ,741 ₃₂]	[290 _{34.8} ,421 _{38.6}]	[552 _{64.1} ,347 _{43.3}]	[165 ₃₁ ,352 _{39.9}]	[451 _{56.9} ,606 _{57.5}]
	778.4 _{60.7}	554.8 _{41.5}	303.2 _{34.1}	367.6 _{43.8}	185.8 _{45.6}	438 _{45.1}

408 The results obtained by the FDT_{ii} technique (Table 7) and those obtained by the kNN_{imp}^C and kNN_{imp}^{Fcons} techniques
409 (Table 8) show that techniques based on kNN_{imp} have globally good behavior. Now, a statistical analysis (Subsection
410 4.3) of the results is performed to decide which technique has the best behavior.

411 First, in order to select the technique that obtains the best accuracy with the least error for the Frost class, the ACC
412 and TPR results are analyzed together for these three techniques. Friedman's test is applied, obtaining a rejection of
413 the null hypothesis (p-value=1.095e-04) with a $\alpha = 0.01$. In other words, it is rejected that there are no significant
414 differences. In this situation, Holm's test is performed on the comparison hypotheses between the kNN_{imp}^C and FDT_{ii}
415 techniques and between the kNN_{imp}^{Fcons} , FDT_{ii} and kNN_{imp}^C techniques. The p-values obtained from this test are 0.2961,
416 0.022665 and 0.004632. Holm's procedure rejects the hypothesis for FDT_{ii} and kNN_{imp}^C , indicating that the kNN_{imp}^{Fcons}
417 technique is statistically better than the other techniques ($\alpha = 0.05$). With respect to the kNN_{imp}^C and FDT_{ii} techniques,
418 there are no significant differences.

419 Secondly, the techniques are analyzed considering their behavior with respect to the E measure (the one that obtains
420 less value of E is better). Friedman's test is applied, obtaining a rejection of the null hypothesis (p-value=4.287e-06)
421 with a $\alpha = 0.01$. In other words, it is rejected that there are no significant differences. In this situation Holm's test is
422 performed on the same comparison hypotheses previously carried out. The p-values obtained are 4.760e-02, 4.041e-
423 05 and 4.041e-05. Holm's procedure rejects the null hypothesis for FDT_{ii} and kNN_{imp}^C , indicating that the kNN_{imp}^{Fcons}
424 technique is statistically better than the other techniques ($\alpha = 0.05$). In addition, the kNN_{imp}^C technique is better than
425 the FDT_{ii} technique ($\alpha = 0.05$).

426 Therefore, the behavior of the three techniques is very satisfactory, highlighting the techniques based on k -nearest
427 neighbors, specifically, the kNN_{imp}^{Fcons} technique. With this analysis, this technique is a candidate for the construction
428 of the decision system.

429 5.2.2. Using datasets for classification with the attributes selected by FDT_{ii} technique

430 Now, the same previous process is performed using only the attributes selected by the FDT_{ii} technique.

431 The kNN_{imp}^F technique is applied to the datasets for classification with selected attributes (the used attributes are
 432 those indicated in the Subsection 5.1). Table 9 shows the results obtained for the different assessment measures by the
 433 kNN_{imp}^F and kNN_{imp}^{Fcons} techniques with selected attributes.

Table 9: Results in % of a 5-fold cross-validation with the datasets with selected attributes (subscripts show standard deviation). For each station and measure, the results obtained by kNN_{imp}^F and kNN_{imp}^{Fcons} are shown, respectively. Values of k used are 9, 9, 13, 11 and 9, for each station respectively.

	CR12	CR32	CI52	JU71	JU81	mean
ACC	[95.2 _{0.5} ,96.5 _{0.4}] 95.84 _{0.4}	[94.8 _{0.2} ,96.1 _{0.3}] 95.40 _{0.3}	[96.5 _{0.2} ,97.7 _{0.2}] 97.02 _{0.3}	[96.1 _{0.4} ,97.3 _{0.4}] 96.73 _{0.4}	[97.0 _{0.3} ,97.8 _{0.3}] 97.36 _{0.25}	[95.9 _{0.3} ,97.1 _{0.3}] 96.47 _{0.3}
TPR	[84.3 _{1.1} ,88.1 _{1.0}] 88.10 _{1.0}	[89.5 _{0.8} ,91.8 _{0.6}] 91.80 _{0.6}	[87.5 _{1.9} ,91.0 _{1.2}] 90.98 _{1.2}	[85.0 _{1.8} ,89.7 _{1.4}] 89.70 _{1.4}	[85.9 _{1.8} ,89.6 _{1.3}] 89.59 _{1.34}	[86.5 _{1.5} ,90.0 _{1.1}] 90.03 _{1.1}
TNR	[97.4 _{0.3} ,98.2 _{0.3}] 97.59 _{0.6}	[96.7 _{0.3} ,97.7 _{0.3}] 96.74 _{0.3}	[98.1 _{0.4} ,98.8 _{0.2}] 98.09 _{0.4}	[97.9 _{0.5} ,98.6 _{0.4}] 97.92 _{0.5}	[98.3 _{0.1} ,98.9 _{0.1}] 98.32 _{0.14}	[97.7 _{0.3} ,98.4 _{0.3}] 97.73 _{0.4}
F-score	[85.6 _{0.9} ,89.5 _{0.7}] 87.78 _{0.6}	[90.3 _{0.8} ,92.8 _{0.7}] 91.53 _{0.8}	[88.2 _{0.3} ,92.0 _{0.5}] 90.12 _{0.7}	[86.2 _{1.0} ,90.7 _{0.9}] 88.80 _{0.9}	[86.1 _{1.5} ,90.1 _{1.0}] 88.15 _{1.09}	[87.3 _{0.9} ,91.0 _{0.8}] 89.28 _{0.8}
E	[657 _{81.5} ,875 _{103.8}] 694 _{63.9}	[565 _{25.2} ,728 _{35.6}] 582.4 _{24.9}	[264 _{42.5} ,370 _{54.4}] 275.6 _{41.6}	[272 _{40.3} ,396 ₅₀] 282.2 _{38.6}	[207 _{31.6} ,281 _{37.1}] 214.8 _{30.9}	[393 _{44.2} ,530 _{56.2}] 409.8 ₄₀

434 The behavior of kNN_{imp}^{Fcons} technique with all attributes and with selected attributes is satisfactory as is shown in the
 435 results in Table 8 and 9, respectively. Now, a statistical analysis of the results is performed to decide which technique
 436 has a better behavior.

437 In order to decide which technique obtains the best accuracy with the least error number for the Frost class, the
 438 ACC and TPR results are analyzed together for these two techniques. Wilcoxon test is applied, obtaining a rejection
 439 of the null hypothesis (p-value=0.000481) with a $\alpha = 0.01$ (at 99.95%). In other words, the test indicates that the
 440 kNN_{imp}^{Fcons} technique with selected attributes is statistically better than the other technique. If the behavior of the
 441 techniques with respect to the E measure is compared, the conclusions are as follows: Wilcoxon test rejects the null
 442 hypothesis (p-value= 0.01732) with a $\alpha = 0.02$ (at 99.27%). Test indicates that the kNN_{imp}^{Fcons} technique with selected
 443 attributes is statistically better than the other technique. And, if the behavior of the techniques is compared with respect
 444 to the measure $F - score$, the conclusions are as follows: Wilcoxon test rejects the null hypothesis (p-value= 9.835e-
 445 07) with a $\alpha = 0.01$ (at 99.99%). Test indicates that the kNN_{imp}^{Fcons} technique with selected attributes is statistically
 446 better than the the kNN_{imp}^{Fcons} technique with all attributes.

447 In Figure 2, radial plots to compare the results obtained by the techniques FDT_{ii} , kNN_{imp}^{Fcons} with all attributes and
 448 kNN_{imp}^{Fcons} with selected attributes regarding the three areas of study are shown. “Noroeste” area includes CR12 and
 449 CR32 stations, “Vega del Segura” area includes CI52 station, and Altiplano area includes JU71 and JU81 stations.

450 In Figure 3, bar graphs to compare kNN_{imp}^C , kNN_{imp}^F and kNN_{imp}^{Fcons} techniques, with and without attributes selected,
 451 regarding to the mean of E measure (classification cost mean) are shown.

452 Figures 2 and 3 show that kNN_{imp}^{Fcons} technique with selected attributes obtains the highest values for ACC, TPR,
 453 TNR and F-Score measures, and the lowest value for E measure, for all areas.

454 In summary, globally and statistically, the technique with the best behaviour is kNN_{imp}^{Fcons} with selected attributes.

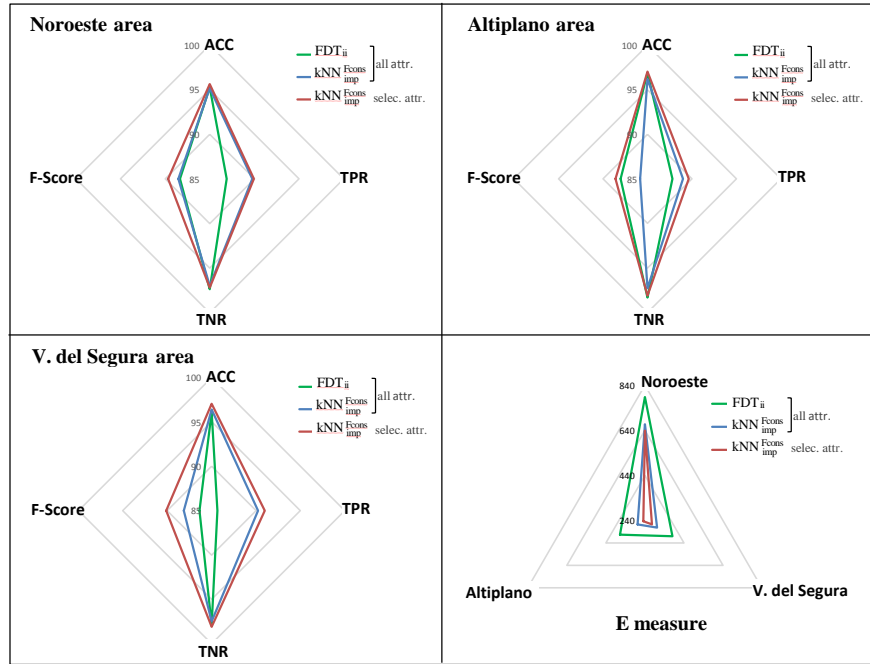


Figure 2: Comparison of the FDT_{ii} , kNN_{imp}^{Fcons} using all attributes and kNN_{imp}^{Fcons} with selected attributes regarding the different measures grouped by the different covered areas.

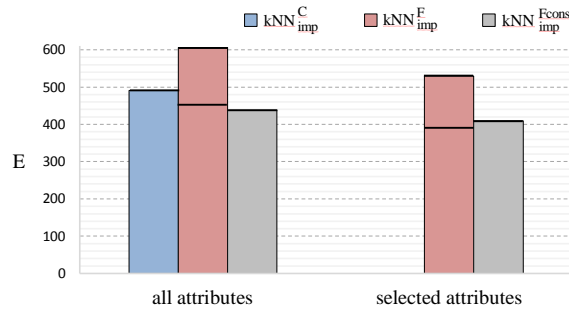


Figure 3: Comparison of the kNN_{imp}^C , kNN_{imp}^F and kNN_{imp}^{Fcons} techniques with respect to measure E using the mean for all stations.

455 Table 10 shows the results obtained by this technique using the training (complete datasets) and the same parameters
 456 used for 5-fold cross-validation.

Table 10: Results in % of train obtained with the kNN_{imp}^{Fcons} technique and datasets for classification with selected attributes.

	CR12	CR32	CI52	JU71	JU81	mean
ACC	96.23	96.11	97.53	97.47	97.70	97.01
TPR	87.01	92.08	90.42	89.75	89.89	89.83
TNR	98.10	97.61	98.77	98.77	98.66	98.38
F-score	88.62	92.78	91.60	91.10	89.55	90.73
E	3570	2756	1395	1339	1019	2015.8

457 5.3. Applying kNN-RegID technique: Predicting the temperature value

458 The proposed kNN-RegID technique is applied to the datasets for regression to infer the value T_{MIN}^{H+1} from the
 459 attributes taken at the current hour and one hour before. Also the different datasets of the stations using only the
 460 attributes selected by FDT_{ii} technique are used (Subsection 5.1). The results obtained are shown in the Table 11.

Table 11: Measurements obtained from 5-fold cross-validation for regression when estimating the T_{MIN}^{H+1} attribute with the kNN-RegID technique and datasets without and with selected attributes. The used k values are 9, 7, 7, 9, 5 and 13, 11, 7, 9, 7, respectively.

	CR12	CR32	CI52	JU71	JU81	mean
<i>MSE</i>	0.8323 _{0.027}	0.8634 _{0.031}	0.6951 _{0.041}	0.9534 _{0.057}	0.5942 _{0.012}	0.7877 _{0.034}
	0.6654 _{0.016}	0.7612 _{0.037}	0.5343 _{0.039}	0.6676 _{0.041}	0.5125 _{0.020}	0.6282 _{0.031}
<i>MAE</i>	0.6909 _{0.011}	0.6812 _{0.014}	0.6166 _{0.010}	0.7310 _{0.022}	0.5796 _{0.008}	0.6599 _{0.013}
	0.6063 _{0.006}	0.6348 _{0.011}	0.5397 _{0.014}	0.6055 _{0.016}	0.5389 _{0.009}	0.5850 _{0.011}
<i>CC</i>	0.9486 _{0.001}	0.9634 _{0.001}	0.9536 _{0.004}	0.9370 _{0.004}	0.9556 _{0.002}	0.9516 _{0.002}
	0.9590 _{0.001}	0.9676 _{0.002}	0.9642 _{0.003}	0.9559 _{0.003}	0.9616 _{0.002}	0.9617 _{0.002}
<i>R²(%)</i>	89.945 _{0.273}	92.751 _{0.298}	90.836 _{0.726}	87.661 _{0.683}	91.252 _{0.314}	90.489 _{0.459}
	91.959 _{0.229}	93.606 _{0.376}	92.956 _{0.638}	91.354 _{0.601}	92.455 _{0.349}	92.466 _{0.439}

461 Applying the statistical tests to the results obtained for MSE and MAE in the Tables 11, it is obtained that there
 462 are significant differences between them with a $\alpha = 0.01$ (p-value=2.98e-08), being the kNN-RegID technique with
 463 selected attributes the best. In addition, as shown these tables, the correlation and determination coefficients have
 464 increased for this technique. Table 12 shows the results for train using this technique with the same values of k as
 465 those used in 5-fold cross-validation. As an example, Figure 4 shows the behavior, during the indicated time periods,
 466 of the inference made by the technique for the attribute T_{MIN}^{H+1} compared with the real values.

Table 12: Measurements obtained from training for regression when estimating the T_{MIN}^{H+1} attribute with the kNN-RegID technique and datasets for regression with selected attributes.

	CR12	CR32	CI52	JU71	JU81	mean
<i>MSE</i>	0.5518	0.6154	0.3884	0.5149	0.3647	0.4870
<i>MAE</i>	0.5504	0.5683	0.4588	0.5290	0.4545	0.5122
<i>CC</i>	0.9661	0.9739	0.9742	0.9661	0.9728	0.9706
<i>R²(%)</i>	93.33	94.84	94.89	93.34	94.64	94.207

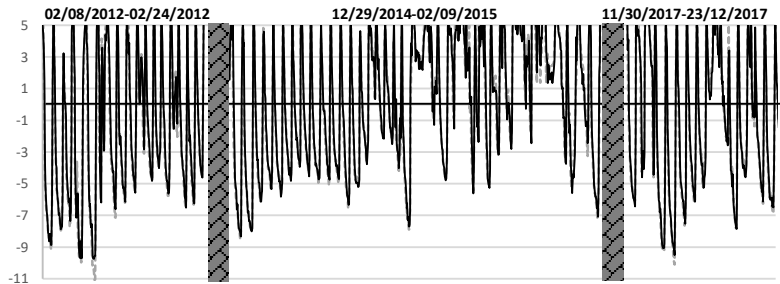


Figure 4: Regression on time periods where different frost events have occurred at CR32 station. The discontinuous gray line represents the real value of the instances and the black line represents the values inferred by kNN-RegID technique and datasets for regression with selected attributes.

467 **6. AFROC: A decision system to Avoid FROst on Crops**

468 The AFROC decision system helps the user to make a decision regarding frost alerts, and therefore, take appropri-
 469 ate actions to reduce its impact. It is therefore a system designed at the operational level. In Figure 5, an illustrative
 470 scheme of the system is shown.

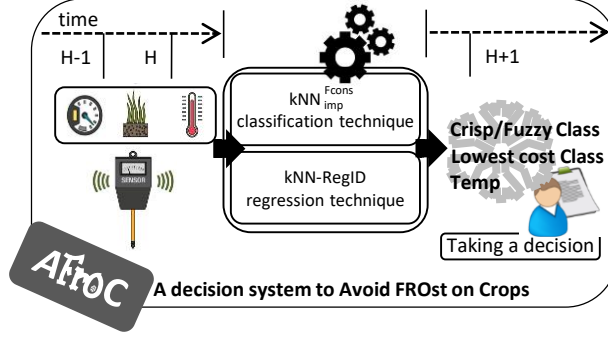


Figure 5: A decision system to prediction of frost.

471 The system uses datasets with all instances and with selected attributes. Therefore, the technique for classification
 472 that is incorporated into the decision system is kNN_{imp}^{Fcons} , with an average accuracy of 97.01% (89.83% sensitivity).
 473 Using this technique, the system provides the fuzzy prediction $\{\mu_F/\text{Frost}, \mu_{nF}/\text{NoFrost}\}$ when $\frac{|\mu_F - \mu_{nF}|}{\max\{\mu_F, \mu_{nF}\}} \leq U_D$, or
 474 the crisp prediction Frost or NoFrost in another case. In addition, the kNN-RegID technique to regression that is
 475 incorporated into the decision system has MSE value of 0.4870 and MAE value of 0.5122.

476 During operation, the system takes as input data the required weather attributes of the current and previous hour
 477 as indicated in the classification and regression models. From these attributes, it is carry out both the frost prediction
 478 ($CLASS_{FnF}$) and the temperature value prediction (T_{MIN}) for the next hour. More specifically, the classification model
 479 provides the crisp prediction Frost or NoFrost, if possible, or the imprecise prediction $\{\mu_F/\text{Frost}, \mu_{nF}/\text{NoFrost}\}$. In
 480 the latter situation, the system reports that the Frost decision is the one with the lowest economic risk (conservative
 481 decision or lowest cost class), but the user, as an expert, can make the most suitable decision based on the degrees μ_F
 482 and μ_{nF} and the temperature value estimated for T_{MIN} .

483 In Table 13 the estimated reply time of the system to the input data is shown, both for obtaining class value and
 484 temperature. The computer used to make these estimates is an Intel Core i7-6700HQ 2.6 GHz with 16GB RAM.

Table 13: Time (in ms) estimated to obtain the inference (classification and regression) in the decision system.

	CR12	CR32	CI52	JU71	JU81	mean
kNN_{imp}^F	25.17	17.04	11.69	10.25	12.32	15.29
kNN-RegID	20.40	16.30	10.78	9.47	11.06	13.60

485 Finally, it is important to highlight that the system is scalable and extensible to any agricultural crop plot. It simply
 486 requires of the technology necessary to collect information of the indicated weather attributes. With this information,
 487 the classification and regression models associated with this plot are created and the AFROC system can now begin to
 488 help farmers. In addition, the U_D parameter must be taken into account when implanting the system. This parameter

489 defines the vagueness of the class value provided by the technique according to the needs of the user. When the system
490 provides a fuzzy class value (fuzzy subset), the uncertainty is maximum since the values of fuzzy subset will have
491 very close membership degrees. Adjusting this parameter causes the user to make their own decisions on a smaller
492 situation number.

493 7. Conclusions

494 This manuscript has been focused on the problem of frost prediction in crops. The problem has been addressed
495 through a process of intelligent data analysis. From the initial dataset composed of a time series data with weather
496 attributes provided by Agricultural Information Service of Murcia Region, the preprocessing phase has allowed to
497 obtain a dataset with fewer instances that maintain the time dependencies and with fewer attributes. The reduction of
498 attributes has been carried out using two strategies: 1) grouping attributes that refer to the same measure in a single
499 attribute expressed by a fuzzy value and 2) performing a selection of the most relevant attributes to carry out the
500 frost prediction from the fuzzy model generated by the FDT_{ii} technique. The information provided by this model has
501 allowed to analyze the relationship between the weather attributes and the orography to predict a frost.

502 As a result of the preprocessing phase, the datasets obtained contain attributes expressed by imprecise values. Be-
503 cause of this, classification and regression techniques capable of dealing with this type of values are needed. Specif-
504 ically, a technique based on the k -nearest neighbors has been proposed for regression and the FDT_{ii} and kNN_{imp}
505 classification techniques have been used. Several experiments have been performed on the available datasets in or-
506 der to find the classification and regression models that provide the best results. The results obtained, supported by
507 statistical tests, indicate that the models obtained from the datasets containing the selected attributes obtain a better
508 result. More specifically, using kNN_{imp}^F technique, which can provide fuzzy class values as an output, and taking a
509 conservative decision (a decision that implies a lower economic cost) the best results are obtained with an average
510 accuracy of 97.01% (89.83% sensitivity). On the other hand, the regression model provided by the kNN-RegID pro-
511 posed technique obtains an MSE precision of 0.4870 and MAE of 0.5122 in the prediction of the temperature value
512 from previous weather values which is quite acceptable.

513 Finally, as a result of the above process, the AFROC decision system has been designed to inform and alert about
514 possible frosts with the aim that the farmer can take appropriate actions to reduce its impact. With the data obtained
515 from the sensors at the current hour and at a previous hour, the system is able to provide the Frost or NoFrost prediction
516 together with the temperature value T_{MIN} for the next hour. The system also provides the degrees of Frost and NoFrost
517 (μ_F and μ_{nF}) allowing the farmer to make the final decision based on his/her experience as an expert. In addition,
518 because the system provides its output from a reduced set of attributes, the number of technological sensors needed
519 decreases, making it easier to implement and maintain the system.

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523 **Conflict of interest**

524 The authors declare that they have no conflict of interest.

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